

# Previous Final exam on Moodle (Answers)

May 12, 2014  
 Time : 90 minutes  
 Spring 2013-14

**MATHEMATICS 218**  
 Final Examination

NAME       /      /        
 ID#       /      /      

Circle your section number :

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|------------------|-----|-----|------------------|-----|-----|--------------|-----|---------|------------------|------|------|
| 1                | 2   | 3   | 4                | 5   | 6   | 7            | 8   | 9       | 10               | 11   | 12   |
| 9 M              | 2 F | 8 M | 1 W              | 2 F | 1 M | 3:30 T       | 5 T | 12:30 T | 1 F              | 11 M | 11 F |

**PART I.** Answer each of the following problems in the space provided for each problem ( Problem 1 to Problem 5).

1. Let  $A = \begin{pmatrix} 5 & 1 & 0 \\ 1 & 5 & 0 \\ 0 & 0 & 6 \end{pmatrix}$

(a) Find the eigenvalues and a basis for each eigenspace of A.

$$|A - \lambda I| = 0 \Rightarrow \begin{vmatrix} 5-\lambda & 1 & 0 \\ 1 & 5-\lambda & 0 \\ 0 & 0 & 6-\lambda \end{vmatrix} = 0 \Rightarrow (6-\lambda) \begin{vmatrix} 5-\lambda & 1 \\ 1 & 5-\lambda \end{vmatrix} = 0$$

[ 10 points ]

$$= (6-\lambda)(25 - 10\lambda + \lambda^2 - 1) = (6-\lambda)(\lambda^2 - 10\lambda + 24) = (6-\lambda)(\lambda-4)(\lambda-6)$$

So  $\lambda_1 = \lambda_2 = 6$ ,  $\lambda_3 = 4$

\* Basis for Eigenspace ( $V_{\lambda_1 = \lambda_2 = 6}$ ) =  $\left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$

\* Basis for Eigenspace ( $V_{\lambda_3 = 4}$ ) =  $\left\{ \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \right\}$

}  $\mathbb{R}^3$   
 So V has 3 linearly indep. eigenvectors  
 So diagonalizable

1(b) Show that A is diagonalizable. Find an invertible matrix P and a diagonal matrix D such that  $P^{-1}AP = D$ . (Do not verify)

Let  $P = \begin{pmatrix} 1 & 0 & -1 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$ ,  $D = \begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{pmatrix}$  [ 6 points ]

$\lambda_1 = \lambda_2 = 6$ ,  $\lambda_3 = 4$

$P^{-1}AP = D = \begin{pmatrix} 6 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 4 \end{pmatrix}$  diagonal matrix

2. Let  $T : P_2 \rightarrow P_2$  be the linear transformation defined by  $T(p(x)) = xp'(x)$ .

(a) Find the matrix  $A = [T]_{\beta}$  of  $T$  relative to the standard ordered basis  $\beta = \{1, x, x^2\}$  of  $P_2$ .

$$T(1) = x(1)' = 0 = 0 \cdot 1 + 0 \cdot x + 0 \cdot x^2 \quad [6 \text{ points}]$$

$$T(x) = x(x)' = x = 0 \cdot 1 + 1 \cdot x + 0 \cdot x^2$$

$$T(x^2) = x(x^2)' = 2x^2 = 0 \cdot 1 + 0 \cdot x + 2 \cdot x^2$$

$$\text{So } A = [T]_{\beta} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

(b) Find the matrix  $B = [T]_{\beta'}$  of  $T$  relative to the ordered basis  $\beta' = \{1+x^2, 2x, 1\}$  of  $P_2$ .

[6 points]

$$T(1+x^2) = x(2x) = 2x^2 = 2 \cdot (1+x^2) + 0 \cdot 2x + (-2) \cdot 1$$

$$T(2x) = x(2x)' = 2x = 0 \cdot (1+x^2) + 1 \cdot 2x + 0 \cdot 1$$

$$T(1) = x(0) = 0 = 0 \cdot (1+x^2) + 0 \cdot 2x + 0 \cdot 1$$

$$\text{So } B = [T]_{\beta'} = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ -2 & 0 & 0 \end{pmatrix}$$

(c) Find the transition matrix  $P = [I]_{\beta'}^{\beta}$  from  $\beta'$  to  $\beta$  such that  $B = P^{-1}AP$  (Do not verify).

[6 points]

$$\beta' = \{1+x^2, 2x, 1\} \quad \text{old}$$

$$\beta = \{1, x, x^2\} \quad \text{new}$$

old

$$I(1+x^2) = 1+x^2 = 1 \cdot 1 + 0 \cdot x + 1 \cdot x^2 \quad \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

$$I(2x) = 2x = 0 \cdot 1 + 2 \cdot x + 0 \cdot x^2 \quad \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix}$$

$$I(1) = 1 = 1 \cdot 1 + 0 \cdot x + 0 \cdot x^2 \quad \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$P = [I]_{\beta'}^{\beta} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

3. Prove that an orthogonal set of nonzero vectors in an inner product space  $V$  is linearly independent.

[10 points]

SEE NOTES

4. Let  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  be the linear transformation defined by

$$T \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a+b+c \\ 0 \\ 0 \end{pmatrix}.$$

Find a basis for the null space  $N(T)$  and use the Gram-Schmidt process to construct an orthonormal basis for  $N(T)$ , with the usual dot product.

[12 points]

$$\begin{pmatrix} a \\ b \\ c \end{pmatrix} \in N(T) \Rightarrow T \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a+b+c \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\text{So } a+b+c=0 \Rightarrow c = -a-b$$

$$\text{So } N(T) = \left\{ \begin{pmatrix} a \\ b \\ -a-b \end{pmatrix} \right\} \quad \text{2 parameters } a, b$$

$$\text{Basis for } N(T) = \left\{ \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \right\}$$

$v_1 \qquad v_2$

Want orthogonal basis

$$\text{Let } w_1 = v_1 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}. \text{ By Gram-Schmidt}$$

$$w_2 = v_2 - \frac{\langle v_2, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} - \frac{\begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}}{\begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}} \cdot \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} -1/2 \\ 1 \\ -1 \end{pmatrix}$$

$$\text{So orthogonal basis of } N(T) = \left\{ \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} -1/2 \\ 1 \\ -1 \end{pmatrix} \right\}$$

$w_1 \qquad w_2$

5. Let  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^4$  and  $S: \mathbb{R}^4 \rightarrow \mathbb{R}^2$  be two linear transformations such that the composition  $S \circ T = 0$ . Show that if  $S$  is onto then  $T$  cannot be one-to-one.

$$\mathbb{R}^3 \xrightarrow{T} \mathbb{R}^4 \xrightarrow{S} \mathbb{R}^2 \quad S \circ T = 0$$

[7 points]

$$\text{So } S \circ T(v) = 0 \Rightarrow S(T(v)) = 0 \Rightarrow R(T) \subseteq N(S)$$

$$\text{So } \dim R(T) \leq \dim N(S)$$

$$S \text{ onto} \Rightarrow \text{Range}(S) = \mathbb{R}^2 \Rightarrow \dim R(S) = 2$$

$$\dim N(S) + \dim R(S) = \dim \mathbb{R}^4 = 4 \Rightarrow \dim N(S) = 4 - 2 = 2$$

Suppose  $T$  is one-to-one, Wait a contradiction

$$\dim N(T) + \dim R(T) = 3 \quad \text{but } N(T) = \{0\}$$

$$\text{So } \dim R(T) = 3 \quad \text{but } R(T) \subseteq N(S) \Rightarrow 3 \leq 2 \quad \text{Contradiction}$$

$\downarrow \dim 3 \qquad \downarrow \dim 2$

So  $T$  cannot be 1-1.

**PART II.** Circle the correct answer for each of the following problems (Problem 6 to Problem 12). IN THE TABLE IN THE FRONT PAGE [3 points for each correct answer]

6. Let  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  be the linear map defined by

$$T \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 3x + 2y \\ -x \\ 0 \end{pmatrix}$$

$R(T) = \left\{ \begin{pmatrix} 3x+2y \\ -x \\ 0 \end{pmatrix} \right\}$   $x, y$  parameters  
 $\dim R(T) = 2$

Then  $\dim(\text{Range } T)$  is:

- a. 3
- b. 2
- c. 1
- d. none of the above.

[3 points]

7. Let  $S$  be the subspace defined by

$S = \{M \text{ is a } 3 \times 3 \text{ skew-symmetric matrix with the sum of the entries of each row is zero}\}$ .

Then  $\dim S =$

- a. 1
- b. 2
- c. 3
- d. none of the above.

$M^T = -M \Rightarrow M = \begin{pmatrix} 0 & a & b \\ -a & 0 & c \\ b & -c & 0 \end{pmatrix}$

$a + b = 0 \Rightarrow b = -a$   
 $-a + c = 0 \Rightarrow c = a$   
 $-b - c = 0 \Rightarrow c = -b = a$

So  $M = \begin{pmatrix} 0 & a & -a \\ -a & 0 & a \\ a & -a & 0 \end{pmatrix}$   
 $\dim S = 1$

[3 points]

8. If  $T: \mathbb{R}^2 \rightarrow \mathbb{R}$  is a linear transformation such that  $T(v) \neq 0$  for some  $v$  in  $\mathbb{R}^2$ , then

- a.  $T$  is one-to-one.
- b.  $T$  is onto.
- c.  $\dim(\text{Nullspace } T) = 0$ .
- d. none of the above.

$\dim(\text{Null}(T)) + \dim(\text{Range } T) = 2$   
 $\frac{0}{\neq}$   
 $0$

$\text{Range}(T) \subset \mathbb{R}^1$   
 $\Rightarrow \dim(\text{Range } T) \leq 1$

[3 points]

$\text{Range } T \neq \{0\}$  since  $T(v) \neq 0$   
 So  $\text{Range } T = \mathbb{R}$   
 $T$  onto

**PART III.** Answer TRUE or FALSE only IN THE TABLE IN THE FRONT PAGE ( 2 points for each correct answer)

- a. ~~T~~ If A is a 3x3 matrix such that  $A^2=0$ , then  $\text{rank } A \neq 3$ . *if rank A = 3  $\Rightarrow$  A invertible so rank  $A^2 \neq 0$*
- b. ~~F~~ Let V be a finite dimensional vector space and let W be a subspace of V. If  $\dim W = \dim V$ , then  $W=V$ . *W subspace of V having same dimension as V*
- c. ~~F~~ If A is a 2x5 matrix, then  $\dim(\text{Column space of } A) \leq 2$ .  *$\dim(N(A)) + \dim(\text{col space}) = 5$  so  $\dim(\text{col } A) \leq 2$*
- d. ~~F~~ Let V be a finite dimensional inner product space and let W be a subspace of V. Then the orthogonal complement of  $W^\perp$  is equal to W. *orth. complement of  $W^\perp = (W^\perp)^\perp = W$*
- e. ~~T~~ Let V be a finite-dimensional vector space and let  $T: V \rightarrow V$  be a linear transformation. If T is one-to-one, then T is onto.  *$\dim N(T) + \dim R(T) = \dim V \Rightarrow R(T) = V$*
- f. ~~F~~ The matrices  $A = \begin{pmatrix} 1 & -2 \\ 3 & 4 \end{pmatrix}$  and  $B = \begin{pmatrix} -2 & 1 \\ 4 & 3 \end{pmatrix}$  are similar.  *$|A| = 10$ ,  $|B| = -10$*
- g. ~~F~~ Let  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$  be a linear transformation such that

$$T \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \text{ and } T \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -2 \\ 3 \end{pmatrix}. \quad \begin{pmatrix} 5 \\ -1 \end{pmatrix} = 5 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + (-1) \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\text{Then } T \begin{pmatrix} 5 \\ -1 \end{pmatrix} = \begin{pmatrix} 4 \\ 7 \\ -2 \end{pmatrix}. \quad T \begin{pmatrix} 5 \\ -1 \end{pmatrix} = 5 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + (-1) \begin{pmatrix} 1 \\ -2 \\ 3 \end{pmatrix} = \begin{pmatrix} 4 \\ 7 \\ -2 \end{pmatrix}$$

- h. ~~F~~ The set of all 2x2 noninvertible matrices is a subspace of  $M_{2 \times 2}$ .

$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

*non invertible + non invertible = invertible*

[16 points].

9. Let  $A = \begin{pmatrix} 2 & 2 \\ 1 & 2 \\ 1 & 1 \end{pmatrix}$  and  $b = \begin{pmatrix} -2 \\ 0 \\ 1 \end{pmatrix}$ . Then the least squares solution to  $Ax = b$  is:

a.  $\hat{x} = \begin{pmatrix} 3/5 \\ 6/5 \end{pmatrix}$

b.  $\hat{x} = \begin{pmatrix} -6/5 \\ 3/5 \end{pmatrix}$

c.  $\hat{x} = \begin{pmatrix} -3/5 \\ 6/5 \end{pmatrix}$

d. None of the above

$$A^T A x = A^T b$$

$$\begin{pmatrix} 2 & 1 & 1 \\ 2 & 2 & 1 \end{pmatrix} \begin{pmatrix} 2 & 2 \\ 1 & 2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 & 1 & 1 \\ 2 & 2 & 1 \end{pmatrix} \begin{pmatrix} -2 \\ 0 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 6 & 7 \\ 7 & 9 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -3 \\ -3 \end{pmatrix}$$

[3 points]  $\begin{cases} 6x + 7y = -3 \\ 7x + 9y = -3 \end{cases} \Rightarrow \begin{cases} x = -6/5 \\ y = 3/5 \end{cases}$

10. Let  $U$  be the subspace of  $\mathbb{R}^3$  defined by

$$U = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 \mid x - 2y + 3z = 0 \right\}. \text{ Then } \dim U^\perp =$$

$x = 2y - 3z \Rightarrow U = \left\{ \begin{pmatrix} 2y-3z \\ y \\ z \end{pmatrix} \right\} \Rightarrow \dim U = 2$   
 $\Rightarrow \dim U^\perp = 3 - 2 = 1$

a. 3

b. 1

c. 2

d. none of the above

[3 points]

11. Let  $A = \begin{pmatrix} 1 & 1 & 2 \\ 0 & 1 & 8 \\ 0 & 1 & 3 \end{pmatrix}$ . Then:

$$\begin{vmatrix} 1-\lambda & 1 & 2 \\ 0 & 1-\lambda & 8 \\ 0 & 1 & 3-\lambda \end{vmatrix} = 0$$

$$(1-\lambda)(3-\lambda+1) - 8 = 0$$

$$(1-\lambda)(\lambda-5)(\lambda+1) = 0$$

a. A is diagonalizable.

b. A is not invertible.

c. The eigenspace corresponding to the eigenvalue  $\lambda=1$  has dimension 2.

d. None of the above.

[3 points]

$\lambda_1 = 1, \lambda_2 = 5, \lambda_3 = -1$   
 3 distinct eigenvalues  
 $\Rightarrow$  diagonalizable

12. Let  $T: V \rightarrow V$  be a linear transformation with  $\dim V = n$  such that  $T$  is onto. Which one of the following statements is FALSE:

a.  $T$  is an isomorphism

b. If  $\{v_1, v_2, \dots, v_n\}$  is linearly independent in  $V$ , then  $\{T(v_1), T(v_2), \dots, T(v_n)\}$  is linearly independent in  $V$ .

c.  $\dim(\text{Range } T) = n$

d. none of the above.

[3 points]

True  $\dim N(T) + \dim R(T) = n = \dim R(T)$  (onto)  $\Rightarrow N(T) = \{0\} \Rightarrow$  invertible  
 True  $c_1 T(v_1) + \dots + c_n T(v_n) = 0 \Rightarrow T(c_1 v_1 + \dots + c_n v_n) = 0$   
 $\Rightarrow c_1 v_1 + \dots + c_n v_n \in N(T) = \{0\}$   
 $\Rightarrow c_1 = \dots = c_n = 0$